

## § Submanifold theory

Goal: Generalize the classical theory for surfaces in  $\mathbb{R}^3$

to submanifolds  $\Sigma^k \subseteq (M^n, g)$

Def<sup>n</sup>: An **isometric immersion**  $F: (\Sigma^k, h) \rightarrow (M^n, g)$

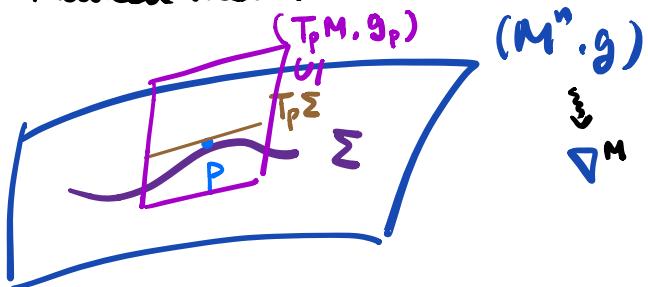
is an immersion (as manifolds) s.t.  $F^*g = h$

As far as local aspects are concerned, we can regard

$$\Sigma^k \subseteq (M^n, g) \quad \text{and} \quad g|_{\Sigma} \text{ induced metric}$$

as a  $k$ -dim'l

embedded submfld



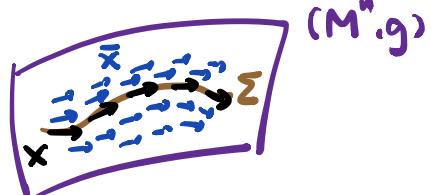
Note:  $(\Sigma^k, g|_{\Sigma})$  Riem mfd Fund Thm  
of R.G.  $\exists!$  Riem connection  $\nabla^{\Sigma}$  on  $\Sigma$

Q: How are the connections  $\nabla^M$  and  $\nabla^{\Sigma}$  related?

Recall:  $\exists$  "canonical" orthogonal splitting: at each  $p \in \Sigma$

$$T_p M = T_p \Sigma \oplus \underbrace{(T_p \Sigma)^{\perp}}_{\text{w.r.t. } g} \quad \text{normal bundle } N_p \Sigma$$

$$v = v^{\top} + v^N$$



Thm: Let  $X, Y \in T(T\Sigma)$ . Then

$$\nabla_X^{\Sigma} Y = (\nabla_{\bar{X}}^M \bar{Y})^{\top}$$

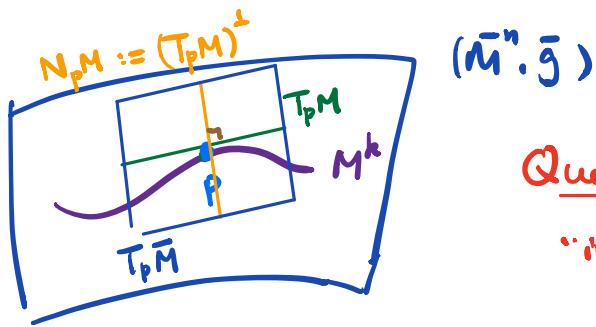
where  $\bar{X}, \bar{Y} \in T(TM)$  are "extensions" of  $X, Y$  s.t.  $\bar{X}|_{\Sigma} = X, \bar{Y}|_{\Sigma} = Y$

Recall: Isometric immersion  $F: (M^k, g) \rightarrow (\bar{M}^n, \bar{g})$  st  $F^* \bar{g} = g$

$$\text{i.e. } \bar{g}_{F(p)}(dF_p(v), dF_p(w)) = g_p(v, w)$$

Locally, immersions are embeddings,  $M^k = F(M) \subseteq \bar{M}^n$ .

Setup:  $M^k \subseteq (\bar{M}^n, \bar{g})$  submanifold ( $k \leq n$ )



Question: How do study the "intrinsic" & "extrinsic" geometry of  $M$ ?

Crucial observation: At  $p \in M$ , there is an

orthogonal splitting  $T_p \bar{M} = T_p M \oplus (T_p M)^\perp$   
(w.r.t.  $\bar{g}$ )

Notation:  $NM := \bigsqcup_{p \in M} (T_p M)^\perp$  normal bundle

orthogonal decomposition

$$V = V^T + V^N \quad \forall p \in M$$

$$T_p \bar{M} \quad T_p M \quad N_p M$$

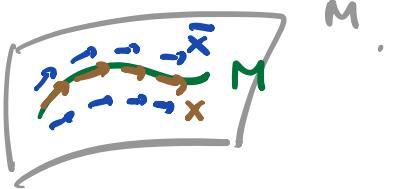
Note:  $\bar{g}$  restricts to an inner product on each  $T_p M \subseteq (T_p \bar{M}, \bar{g})$

write  $g := \bar{g}|_{T_p M} \rightsquigarrow (M^k, g)$  Riem. manifold

By Fund. Thm. of R.G.,  $\exists!$  Riem. connection  $\nabla$  for  $(M^k, g)$ .

Q: How is  $\nabla$  related to the ambient Riem. connection  $\bar{\nabla}$  on  $(\bar{M}, \bar{g})$ ?

Recall:  $\nabla : T(TM) \times T(TM) \rightarrow T(TM)$



$\bar{\nabla} : T(T\bar{M}) \times T(T\bar{M}) \rightarrow T(T\bar{M})$

Prop: Let  $X, Y \in T(TM)$ , and  $\bar{X}, \bar{Y} \in T(T\bar{M})$  be extensions of  $X, Y$ .

THEN:

$$\nabla_X Y = (\bar{\nabla}_{\bar{X}} \bar{Y})^T$$

Remarks:  $\bar{\nabla}_{\bar{X}} \bar{Y}(p)$  depends only on  $\bar{X}(p) = X(p)$

and  $\bar{Y}$  along any curve  $\gamma : (-\epsilon, \epsilon) \rightarrow \bar{M}$  s.t.  $\gamma(0) = p$ ,  $\gamma'(0) = X(p)$

[we can make  $\gamma \subseteq M$ , where  $\bar{Y} = Y$  on  $M$ ]

$\Rightarrow$  R.H.S. is indep. of the choice of extensions  $\bar{X}, \bar{Y}$ .

Proof: Check R.H.S. defines a connection which is metric compatible  
and torsion-free, then result follows by uniqueness part  
of Fund Thm of R.G.

(i)  $(X, Y) \mapsto (\bar{\nabla}_X Y)^T$  bilinear

(ii)  $(\bar{\nabla}_{fX} Y)^T = (f \bar{\nabla}_X Y)^T = f (\bar{\nabla}_X Y)^T$

(iii)  $(\bar{\nabla}_X (fY))^T = (X(f)Y + f \bar{\nabla}_X Y)^T = X(f)Y + f (\bar{\nabla}_X Y)^T$

(iv)  $\bar{g}(S(X, Y)) = \bar{g}(\bar{g}(\bar{X}, \bar{Y})) = \bar{g}(\bar{\nabla}_{\bar{X}} \bar{Y}, Y) + \bar{g}(X, \bar{\nabla}_{\bar{Y}} \bar{Y})$   
 $= g((\bar{\nabla}_{\bar{X}} \bar{Y})^T, Y) + g(X, (\bar{\nabla}_{\bar{Y}} \bar{Y})^T)$

(v)  $(\bar{\nabla}_{\bar{X}} \bar{Y})^T - (\bar{\nabla}_{\bar{Y}} \bar{X})^T = (\bar{\nabla}_{\bar{X}} \bar{Y} - \bar{\nabla}_{\bar{Y}} \bar{X})^T = ([\bar{X}, \bar{Y}])^T$  } torsion-free  
 $= ([X, Y])^T = [X, Y]$

Connection.

metric-compatible

torsion-free

Q: What about the "normal" part of  $\bar{\nabla}$ ?

Def<sup>n</sup>: 2<sup>nd</sup> fundamental form of M in  $\bar{M}$

$$A : T(TM) \times T(TM) \longrightarrow T(NM)$$

$$A(X, Y) := (\bar{\nabla}_{\bar{X}} \bar{Y})^N$$

Remark: This is well-defined indep. of the extensions  $\bar{X}, \bar{Y}$ .

Lemma: (i)  $A(X, Y) = A(Y, X)$

$$\forall X, Y \in T(TM) \\ \forall f \in C^\infty(M)$$

$$(ii) A(fX, Y) = A(X, fY) = f A(X, Y)$$

i.e. A is a symmetric NM-valued (0,2)-tensor.

Proof: (i)  $A(X, Y) - A(Y, X) = (\bar{\nabla}_{\bar{X}} \bar{Y})^N - (\bar{\nabla}_{\bar{Y}} \bar{X})^N$

$$= (\bar{\nabla}_{\bar{X}} \bar{Y} - \bar{\nabla}_{\bar{Y}} \bar{X})^N = ([\bar{X}, \bar{Y}])^N = ([X, Y])^N = 0$$

(Because  $[X, Y] \in T(TM) \quad \forall X, Y \in T(TM)$ ).

$$(ii) A(fX, Y) = (\bar{\nabla}_{f\bar{X}} \bar{Y})^N = (\bar{f} \bar{\nabla}_{\bar{X}} \bar{Y})^N = f(\bar{\nabla}_{\bar{X}} \bar{Y})^N = f A(X, Y).$$


---

Fix  $\eta \in T(NM)$ , then we can define a scalar-valued 2<sup>nd</sup>. ff. (w.r.t  $\eta$ )

$$A_\eta : T(TM) \times T(TM) \longrightarrow C^\infty(M)$$

$$A_\eta(X, Y) = \langle A(X, Y), \eta \rangle$$

This is a symmetric bilinear form on each  $T_p M$ .

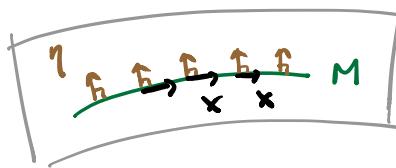
linear  
maps  
algebra

$$A_\eta(X, Y) = \langle S_\eta(X), Y \rangle$$

shape operator /  
Weingarten map

where  $S_\eta : T_p M \rightarrow T_p M$  is self-adjoint operator.

Prop:  $S_\eta(x) = -(\bar{\nabla}_x \eta)^T$



M

Proof:  $\langle S_\eta(x), Y \rangle = A_\eta(x, Y) = \langle A(x, Y), \eta \rangle$

$$= \langle (\bar{\nabla}_{\bar{x}} \bar{Y})^N, \eta \rangle = \langle \bar{\nabla}_{\bar{x}} \bar{Y}, \eta \rangle$$

$$= X \underbrace{\langle Y, \eta \rangle}_{\equiv 0} - \langle Y, \bar{\nabla}_x \eta \rangle = \langle Y, -(\bar{\nabla}_x \eta)^T \rangle$$

$\forall x, Y \in T(TM)$

□

Question:

$(\bar{M}^n, \bar{g})$   $\rightsquigarrow$  connection  $\bar{\nabla}$   $\rightsquigarrow$  Curvature  $\bar{R}$

UI

related ↑

↓ relation?

$(M^k, g)$   $\rightsquigarrow$  connection  $\nabla$   $\rightsquigarrow$  curvature  $R$

Answer:  $\bar{R}$  and  $R$  are related via the 2<sup>nd</sup> f.f.  $A$  (or  $S_\eta$ )

They will be expressed in terms of 3 sets of "constraint equations" called Gauss, Codazzi, Ricci equations.

Before we state these equations, we need some preliminary notions:

(i) Connection & curvature on normal bundle NM

$\exists$  connection  $\nabla^\perp$  on  $NM$  defined as:

$$\nabla^\perp : T(TM) \times T(NM) \rightarrow T(NM)$$

$$\nabla_x^\perp \eta := (\bar{\nabla}_x \eta)^N$$

(Ex: This is a  
"connection")

$\rightsquigarrow$  normal curvature  $R^\perp(x, Y) \eta := \nabla_Y^\perp \nabla_x^\perp \eta - \nabla_x^\perp \nabla_Y^\perp \eta + \nabla_{[x, Y]}^\perp \eta$

(ii) Covariant derivative of 2<sup>nd</sup> ff. A

Fix  $\eta \in T(NM)$ , then

$$A_\eta(x, Y) = \langle A(x, Y), \eta \rangle =: A(x, Y, \eta)$$

regard  $A : T(TM) \times T(TM) \times T(NM) \rightarrow C^\infty(M)$

Define:  $\forall x, Y, Z \in T(TM), \forall \eta \in T(NM),$

$$\begin{aligned} (\nabla_Z A)(x, Y, \eta) := & Z(A(x, Y, \eta)) - A(\nabla_Z x, Y, \eta) \\ & - A(x, \nabla_Y Z, \eta) - A(x, Y, \nabla_Z^\perp \eta) \end{aligned}$$

Thm: ("Constraint Equations" for isometric immersions)

The following equations hold for  $M \subseteq (\bar{M}, \bar{g})$ :

$\forall x, Y, Z, W \in T(TM), \forall \eta, \zeta \in T(NM)$ . we have

Gauss:  $\bar{R}(x, Y, Z, W) = R(x, Y, Z, W) - \underbrace{\langle A(Y, W), A(x, Z) \rangle}_{T T} + \underbrace{\langle A(x, W), A(Y, Z) \rangle}_{T T}$

Ricci:  $\bar{R}(x, Y, \underbrace{\eta, \zeta}_{N N}) = \underbrace{\langle R^\perp(x, Y) \eta, \zeta \rangle}_{\text{Commutator}} + \underbrace{\langle [S_\eta, S_\zeta](x), Y \rangle}_{S_\eta \circ S_\zeta - S_\zeta \circ S_\eta}$

Codazzi:  $\bar{R}(x, Y, \underbrace{Z, \eta}_{T N}) = (\nabla_Y A)(x, Z, \eta) - (\nabla_X A)(Y, Z, \eta)$

Idea of Proof:  $\exists$  orthogonal splitting  $T\bar{M} = TM \oplus NM$

Proof: Recall:  $\bar{\nabla}_x Y = \nabla_x Y + A(x, Y)$

: tangent to M

: normal to M

$$\begin{aligned}
 \bar{R}(x, Y) Z &:= \bar{\nabla}_Y \bar{\nabla}_x Z - \bar{\nabla}_x \bar{\nabla}_Y Z + \bar{\nabla}_{[x, Y]} Z \\
 &= \bar{\nabla}_Y (\nabla_x Z + A(x, Z)) - \bar{\nabla}_x (\nabla_Y Z + A(Y, Z)) \\
 &\quad + \nabla_{[x, Y]} Z + A([x, Y], Z) \\
 &= \nabla_Y \nabla_x Z + A(Y, \nabla_x Z) + \bar{\nabla}_Y (A(x, Z)) \\
 &\quad - \nabla_x \nabla_Y Z - A(x, \nabla_Y Z) - \bar{\nabla}_x (A(Y, Z)) \\
 &\quad + \nabla_{[x, Y]} Z + A([x, Y], Z) \\
 &= R(x, Y) Z + A(Y, \nabla_x Z) - A(x, \nabla_Y Z) + A([x, Y], Z) \\
 &\quad + \bar{\nabla}_Y (A(x, Z)) - \bar{\nabla}_x (A(Y, Z)).
 \end{aligned}$$

Taking inner product with a tangential  $W \in T(TM)$ .

$$\begin{aligned}
 \bar{R}(x, Y, Z, W) &= R(x, Y, Z, W) + \langle \bar{\nabla}_Y (A(x, Z)), W \rangle - \langle \bar{\nabla}_x (A(Y, Z)), W \rangle \\
 &= R(x, Y, Z, W) - \langle A(x, Z), \bar{\nabla}_Y W \rangle + \langle A(Y, Z), \bar{\nabla}_x W \rangle \\
 &= R(x, Y, Z, W) - \langle A(x, Z), (\bar{\nabla}_Y W)^N \rangle + \langle A(Y, Z), (\bar{\nabla}_x W)^N \rangle \\
 \text{Gauss!} \quad &= R(x, Y, Z, W) - \langle A(x, Z), A(Y, W) \rangle + \langle A(Y, Z), A(X, W) \rangle
 \end{aligned}$$

Taking inner product with a normal  $\eta \in T(NM)$ .

$$\begin{aligned}
 \bar{R}(x, Y, Z, \eta) &= A(Y, \nabla_x Z, \eta) - A(x, \nabla_Y Z, \eta) + A([x, Y], Z, \eta) \\
 &\quad + \underbrace{\langle \bar{\nabla}_Y (A(x, Z)), \eta \rangle}_{\text{green}} - \underbrace{\langle \bar{\nabla}_x (A(Y, Z)), \eta \rangle}_{\text{green}}
 \end{aligned}$$

Note:  $\langle \bar{\nabla}_Y(A(x, z)), \eta \rangle$

$$= Y(A(x, z, \eta)) - \langle A(x, z), (\bar{\nabla}_Y \eta)^N \rangle$$

$$= Y(A(x, z, \eta)) - \langle A(x, z), \nabla_Y^\perp \eta \rangle$$

$$\begin{aligned} \bar{R}(x, Y, z, \eta) &= \underline{A(Y, \nabla_x z, \eta)} - \underline{A(x, \nabla_Y z, \eta)} + \underline{A(\nabla_x Y - \nabla_Y x, z, \eta)} \\ &\quad + \underline{Y(A(x, z, \eta))} - \underline{A(x, z, \nabla_Y^\perp \eta)} \\ &\quad - \underline{X(A(Y, z, \eta))} + \underline{A(Y, z, \nabla_X^\perp \eta)} \\ &= \underline{(\nabla_Y A)(x, z, \eta)} - \underline{(\nabla_x A)(Y, z, \eta)} \end{aligned}$$

Recall:  $\bar{\nabla}_x \eta = -S_\eta(x) + \nabla_X^\perp \eta$

$$\begin{aligned} \bar{R}(x, Y) \eta &= \bar{\nabla}_Y \bar{\nabla}_x \eta - \bar{\nabla}_x \bar{\nabla}_Y \eta + \bar{\nabla}_{[x, Y]} \eta \\ &= \bar{\nabla}_Y (-S_\eta(x) + \nabla_X^\perp \eta) - \bar{\nabla}_x (-S_\eta(Y) + \nabla_Y^\perp \eta) \\ &\quad - S_\eta([x, Y]) + \nabla_{[x, Y]}^\perp \eta \\ &= \text{"Tangential terms"} \\ &\quad - [\bar{\nabla}_Y(S_\eta(x))]^N + [\bar{\nabla}_x(S_\eta(Y))]^N \\ &\quad + \nabla_Y^\perp \nabla_X^\perp \eta - \nabla_X^\perp \nabla_Y^\perp \eta + \nabla_{[x, Y]}^\perp \eta \end{aligned}$$

Taking inner product with a normal  $\zeta \in T(NM)$ .

$$\bar{R}(x, Y, \eta, \zeta) = \langle R^\perp(x, Y) \eta, \zeta \rangle$$

$$- \langle [\bar{\nabla}_Y(S_\eta(x))]^N, \zeta \rangle + \langle [\bar{\nabla}_x(S_\eta(Y))]^N, \zeta \rangle$$

Note:  $\langle [\bar{\nabla}_Y(S_\eta(x))]^\eta, \zeta \rangle = \langle \bar{\nabla}_Y(S_\eta(x)), \zeta \rangle$

$$= Y(\underbrace{\langle S_\eta(x), \zeta \rangle}_{\equiv 0}) - \langle S_\eta(x), (\bar{\nabla}_Y \zeta)^\top \rangle$$

$$= \langle S_\eta(x), S_\zeta(Y) \rangle$$

$$\bar{R}(x, Y, \eta, \zeta) = \underbrace{\langle R^\perp(x, Y)\eta, \zeta \rangle}_{\text{Ricci!}} + \langle S_\eta(x), S_\zeta(Y) \rangle - \langle S_\eta(Y), S_\zeta(x) \rangle$$

$$= \langle R^\perp(x, Y)\eta, \zeta \rangle + \langle (S_\zeta \circ S_\eta - S_\zeta \circ S_\eta)(x), Y \rangle$$


---

### Several Remarks

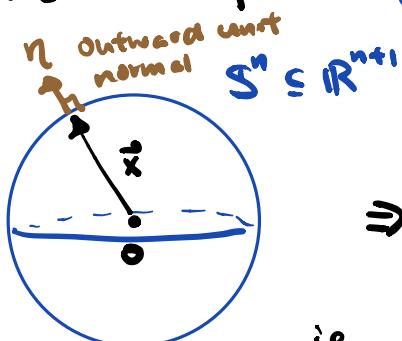
(1) In codimension 1 (i.e. hypersurface), the Ricci equation is trivial.

Reason:  $\text{codim } 1 \Leftrightarrow NM$  is 1-dim'l  $\zeta = f\eta$

Ricci:  $\bar{R}(x, Y, \eta, \eta) = \underbrace{\langle R^\perp(x, Y)\eta, \eta \rangle}_{\equiv 0} + \underbrace{\langle [S_\eta, S_\eta](x), Y \rangle}_{\equiv 0}$

(2) The unit sphere  $S^n \subseteq (\mathbb{R}^{n+1}, \bar{g}_{\text{Eucl.}})$  has  $K \equiv 1$ .

Pf:



$$S^n \subseteq \mathbb{R}^{n+1}$$

$$\eta = \vec{x} \quad \text{position vector}$$

$$\Rightarrow \bar{\nabla}_{\vec{x}} \eta = \bar{\nabla}_{\vec{x}} \vec{x} = \vec{x} \Rightarrow S_\eta(x) = -\vec{x}$$

$$\text{i.e. } A_\eta(x, Y) = \langle S_\eta(x), Y \rangle = -\langle \vec{x}, Y \rangle$$

$$\text{Gauss: } \underbrace{\bar{R}(x,y,z,w)}_{\equiv 0} = R(x,y,z,w) - \langle A(y,w), A(x,z) \rangle + \langle A(x,w), A(y,z) \rangle$$

$\therefore \bar{R}^{\text{ext}}$  is flat

$$\Rightarrow R^{\mathbb{S}^n}(x,y,z,w) = \langle Y,W \rangle \langle X,Z \rangle - \langle X,W \rangle \langle Y,Z \rangle$$

ie  $K^{\mathbb{S}^n} \equiv 1$ .

---

(iii) If  $M^{n-1} \subset (\bar{M}^n, \bar{g})$  codim 1 and  $(\bar{M}, \bar{g})$  has constant sectional curvature, then for  $\eta$  = unit normal (locally)

$$\text{Codazzi eq}^2 \Leftrightarrow \nabla_x(S_\eta(Y)) - \nabla_Y(S_\eta(X)) = S_\eta([X,Y])$$

(Ex: Prove this.)

Summary: Submanifold  $M^k \subseteq (\bar{M}^n, \bar{g})$ ,  $\bar{g}|_M =: g$

→ Study  $(M^k, g)$  from two perspectives: intrinsic OR extrinsic

Roughly speaking:  $T_p \bar{M} = T_p M \oplus (T_p M)^\perp$

"differentiate  $g$ "  
→

$$\bar{\nabla} = \begin{matrix} \bar{\nabla}^T \\ \bar{\nabla}^N \end{matrix}$$

$\bar{\nabla}^T$   
Riem. conn.  
on  $(\bar{M}, \bar{g})$

$\bar{\nabla}^N$   
Riem. conn.  
on  $(M, g)$

2<sup>nd</sup> f.f.  $A(X,Y) := (\bar{\nabla}_X Y)^N$   
Equivalently.  $S_\eta(X) := -(\bar{\nabla}_X \eta)^T$   
 $\eta \in T(NM)$

"differentiate  $g$  twice"  
→ 3 "constraint eq<sup>2</sup>"

Note:  $\langle A(X,Y), \eta \rangle = \langle S_\eta(X), Y \rangle$

$$\underline{\text{Gauss}}: \bar{R}(x, y, z, w) = R(x, y, z, w) - \langle A(y, w), A(x, z) \rangle + \langle A(x, w), A(y, z) \rangle$$

$$\underline{\text{Codazzi}}: \bar{R}(x, y, z, \eta) = (\nabla_y A)(x, z, \eta) - (\nabla_x A)(y, z, \eta)$$

$$\underline{\text{Ricci}}: \bar{R}(x, y, \eta, \zeta) = \langle R^\perp(x, y)\eta, \zeta \rangle + \langle [S_\eta, S_\zeta](x), y \rangle$$

Consider the special case of  $M^2 \subset (\mathbb{R}^3, g_{\text{Eucl.}})$

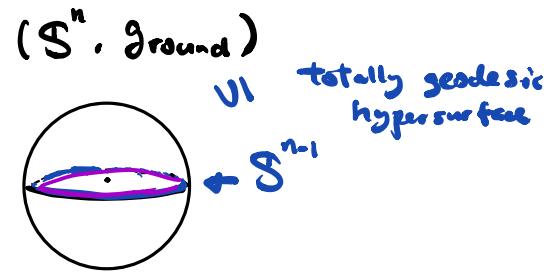
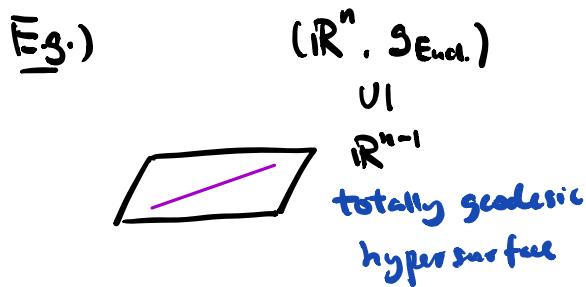
Fix  $p \in M$ ,  $\sigma = T_p M \subseteq T_p \mathbb{R}^3$        $\sigma = \text{Span}\{e_1, e_2\}$  O.N.B.

$$\bar{R}(e_1, e_2, e_1, e_2) = R(e_1, e_2, e_1, e_2) - \langle A(e_2, e_2), A(e_1, e_1) \rangle \\ (\because \mathbb{R}^3 \text{ is flat}) \qquad \qquad \qquad + \langle A(e_1, e_2), A(e_2, e_1) \rangle$$

$$\Rightarrow 0 = R_{1212} - A_{22}A_{11} + A_{12}^2 \quad \xrightarrow{\text{Gauss' Golden Theorem!}}$$

$$\text{i.e. } R_{1212} = A_{11}A_{22} - A_{12}^2 = \det \begin{pmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{pmatrix} =: K \quad \begin{matrix} \text{Gauss} \\ \text{curvature} \end{matrix}$$

Def<sup>n</sup>:  $M^k \subseteq (\bar{M}^n, \bar{g})$  is **totally geodesic** if  $A \equiv 0$  at every  $p \in M$



Prop:  $M^k \subseteq (\bar{M}^n, \bar{g})$  totally geodesic  $\Leftrightarrow$  every geodesics in  $M$  are geodesics in  $\bar{M}$ .

Pf: For any smooth curve  $\gamma: I \rightarrow M$ ,

$$\bar{\nabla}_{\gamma'} \gamma' = (\bar{\nabla}_\gamma \gamma')^\top + (\bar{\nabla}_\gamma \gamma')^\perp$$

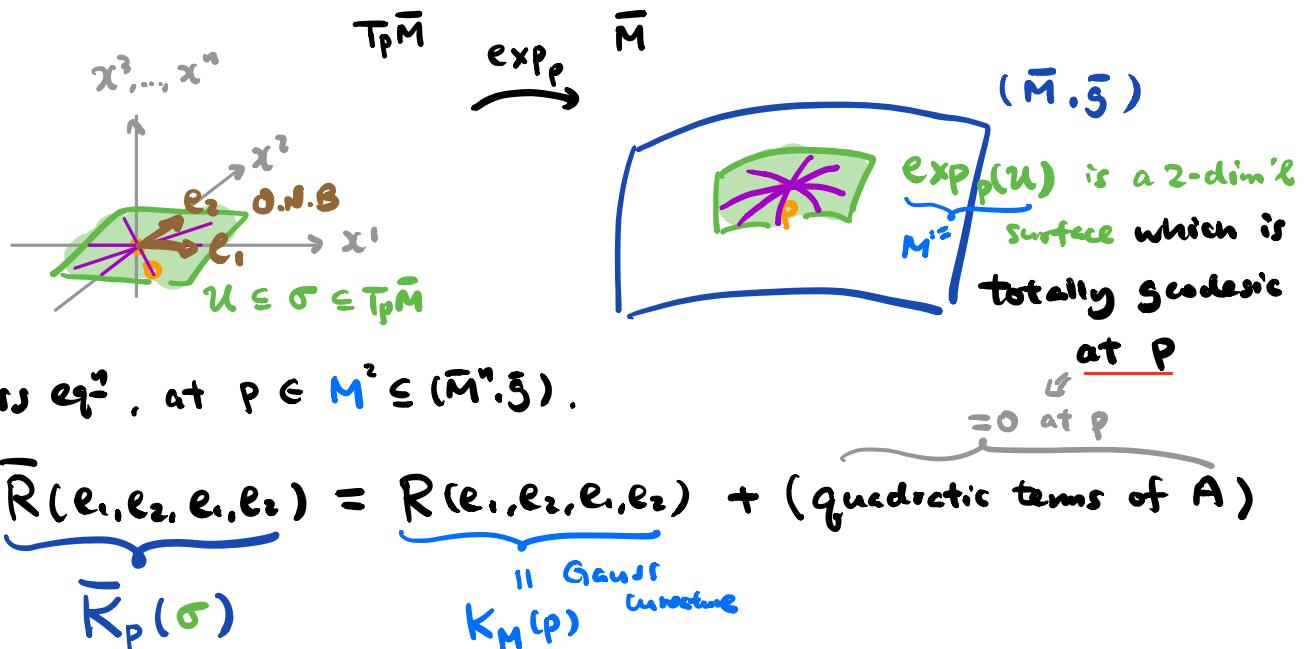
$$= \nabla_{\gamma'} \gamma' + \underbrace{A(\gamma', \gamma')}_{\equiv 0} \\ \because \text{totally geodesic}$$

Note: Geodesics in  $\bar{M}$  lying in orde  $M$  are always geodesic in  $M$

— — — — —

This gives a geometric interpretation of "Sectional Curvature" in terms of "Gauss curvature" for surfaces.

Recall: In geodesic normal coord. centered at  $p \in (\bar{M}, \bar{g})$ .



By Gauss eq<sup>2</sup>, at  $p \in M^k \subseteq (\bar{M}^n, \bar{g})$ .

$$\overline{R}(e_1, e_2, e_1, e_2) = \underbrace{R(e_1, e_2, e_1, e_2)}_{\overline{K}_p(\sigma)} + \underbrace{\text{(quadratic terms of } A\text{)}}_{\parallel \text{Gauss curvature } K_M(p)}$$

Remark: Totally geodesic submanifolds rarely exists in general  $(\bar{M}^n, \bar{g})$ .

We want to define a "weaker" notion.

Def<sup>2</sup>:  $M^k \subseteq (\bar{M}^n, \bar{g}) \rightsquigarrow$  The mean curvature vector at  $p \in M$

$$\vec{H}(p) := \sum_{i=1}^k A_p(e_i, e_i) \quad \text{where } \{e_1, \dots, e_k\} \text{ O.N.B. for } T_p M$$

And we say  $M$  is **minimal** if  $\vec{H} \equiv \vec{0}$  at every  $p \in M$

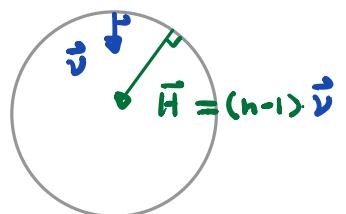
Remarks: 1) totally geodesic  $\iff$  minimal

E.g.)  $S^{n-1} \subseteq \mathbb{R}^n$

2) In codim. 1 case, we write

$$\vec{H} = H \vec{v}$$

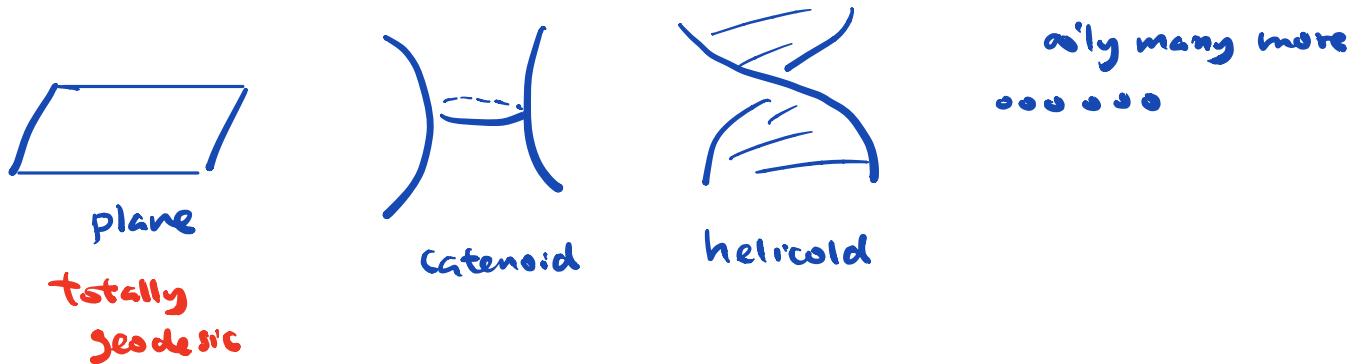
↑ unit normal  
(scalar)  
mean curvature (Sign depends on choice of  $\vec{v}$ )



3) When  $k = \dim M = 1$ , then "minimal"  $\Leftrightarrow$  "geodesic"

In fact, minimal  $k$ -submanifolds are critical points to the  $k$ -dim'l area functional, just like "geodesics" are critical points to the length functional.

E.g.) Minimal surfaces in  $\mathbb{R}^3$



Minimal surfaces in  $(S^3, \text{round})$

